Theory meets experiment 2025 New frontiers in particle cosmology

> Will Handley <wh260@cam.ac.uk>

Royal Society University Research Fellow Institute of Astronomy, University of Cambridge Kavli Institute for Cosmology, Cambridge Gonville & Caius College willhandley.co.uk/talks

7<sup>th</sup> January 2024







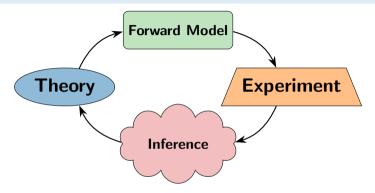




<wh260@cam.ac.uk>

## **TMEX:** Theory meets experiment

New frontiers in particle cosmology

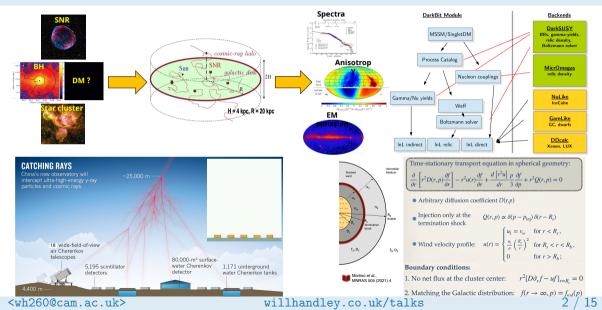


- Inference sits at the interface between theory and experiment
- Also called "inverse problems"
- Process is direct: "measurement"

<wh260@cam.ac.uk>

- This talk focuses on frontiers:
- 1. Simulation-based inference
- 2. GPU-accelerated inference

## Examples of forward models from Monday



## Bayesian & frequentist data combination

Multimessenger approaches

## Frequentist

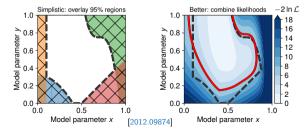
- Preferred by particle physicists & mathematicians
- Probability/stochasticity only in the data D
- Whether Bayesian or frequentist, If you have a model *M* with parameters θ, multiple datasets combine at the likelihood level:

$$P(D_1, D_2|\theta, M) = P(D_1|\theta, M)P(D_2|\theta, M)$$

$$\mathcal{L}_{joint} = \mathcal{L}_1 \times \mathcal{L}_2 \times \ldots \times \mathcal{L}_n$$

#### **Bayesian**

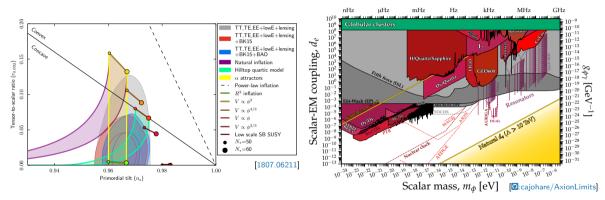
- Preferred by astronomers & machine learning/information theorists
- Quantifies all uncertainties in data & model (D, θ, M) using probability.



<wh260@cam.ac.uk>

## An aside: difference in plotting

#### Exclusion vs. posterior plots



- Contours indicate allowed regions
- Preferred in astro/cosmology

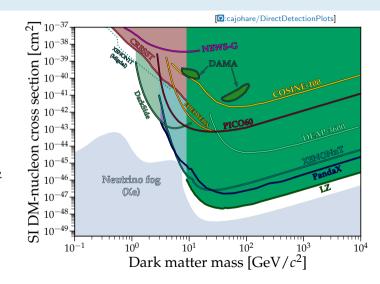
- Contours indicate excluded regions
- Preferred in particle physics

#### <wh260@cam.ac.uk>

## An aside: difference in plotting

**Exclusion vs. posterior plots** 

- Beware this kind of particularly confusing plot, which uses both!
- Here almost all of these are  $2\sigma$  exclusion plots
- But 'DAMA' are (controversial & conflicting) superimposed constraints/allowed regions.



<wh260@cam.ac.uk>

## The three pillars of (Bayesian) inference

#### **Parameter estimation**

What do the data tell us about the parameters of a model? e.g. the size or age of a  $\land CDM$  universe

#### Model comparison

How much does the data support a particular model? *e.g.*  $\Lambda CDM$  vs a dynamic dark energy cosmology

#### **Tension quantification**

Do different datasets make consistent predictions from the same model? *e.g. CMB vs Type IA supernovae data* 

 $\mathcal{R} = \frac{\mathcal{Z}_{AB}}{\mathcal{Z}_{A}\mathcal{Z}_{B}}$ 

$$g S = \langle \log \mathcal{L}_{AB} \rangle_{\mathcal{P}_{AB}} \\ - \langle \log \mathcal{L}_{A} \rangle_{\mathcal{P}_{A}} \\ - \langle \log \mathcal{L}_{B} \rangle_{\mathcal{P}_{B}}$$

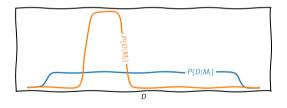
<wh260@cam.ac.uk>

## Model comparison $\mathcal{Z} = P(D|M)$

Bayesian model comparison allows mathematical derivation of key philosophical principles. Viewed from data-space D: Viewed from parameter-space  $\theta$ :

## **Popper's falsificationism**

- Prefer models that make bold predictions.
- if proven true, model more likely correct.



Falsificationism comes from normalisation

## Occam's razor

- Models should be as simple as possible
- ... but no simpler
- Occam's razor equation:

$$\log \mathcal{Z} = \langle \log \mathcal{L} \rangle_{\mathcal{P}} - \mathcal{D}_{\mathsf{KL}}$$

"Occam penalty": KL divergence between prior  $\pi$  and posterior  $\mathcal{P}$ .



<wh260@cam.ac.uk>

willhandley.co.uk/talks

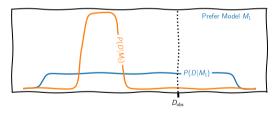
15

## Model comparison $\mathcal{Z} = P(D|M)$

Bayesian model comparison allows mathematical derivation of key philosophical principles. Viewed from data-space D: Viewed from parameter-space  $\theta$ :

## **Popper's falsificationism**

- Prefer models that make bold predictions.
- if proven true, model more likely correct.



Falsificationism comes from normalisation

## Occam's razor

- Models should be as simple as possible
- ... but no simpler
- Occam's razor equation:

$$\log \mathcal{Z} = \langle \log \mathcal{L} \rangle_{\mathcal{P}} - \mathcal{D}_{\mathsf{KL}}$$

"Occam penalty": KL divergence between prior  $\pi$  and posterior  $\mathcal{P}$ .



15

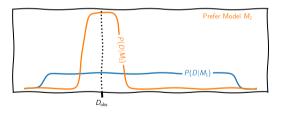
<wh260@cam.ac.uk>

## Model comparison $\mathcal{Z} = P(D|M)$

Bayesian model comparison allows mathematical derivation of key philosophical principles. Viewed from data-space D: Viewed from parameter-space  $\theta$ :

## **Popper's falsificationism**

- Prefer models that make bold predictions.
- if proven true, model more likely correct.



Falsificationism comes from normalisation

## Occam's razor

- Models should be as simple as possible
- ... but no simpler
- Occam's razor equation:

$$\log \mathcal{Z} = \langle \log \mathcal{L} \rangle_{\mathcal{P}} - \mathcal{D}_{\mathsf{KL}}$$

"Occam penalty": KL divergence between prior  $\pi$  and posterior  $\mathcal{P}$ .

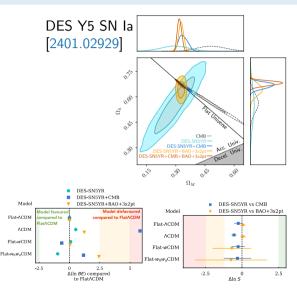


<wh260@cam.ac.uk>

The standard approach if you are fortunate enough to have a likelihood function  $P(D|\theta)$ :

$$P(\theta|D) = rac{P(D|\theta)P(\theta)}{P(D)}$$

- 1. Define prior  $\pi(\theta)$ 
  - spend some time being philosophical
- 2. Sample posterior  $\mathcal{P}(\theta|D)$ 
  - use out-of-the-box MCMC tools such as emcee or MultiNest
  - make some triangle plots
- 3. Optionally compute evidence  $\mathcal{Z}(D)$ 
  - e.g. nested sampling or parallel tempering
  - do some model comparison (i.e. science)
  - talk about tensions



#### <wh260@cam.ac.uk>

The standard approach if you are fortunate DES Y5 SN la enough to have a likelihood function  $P(D|\theta)$ : 2401.02929 Likelihood × Prior  $P(\theta|D) = \frac{P(D|\theta)P(\theta)}{P(D)}$ Posterior =0.70 Fvidence 0.60 ΩV Define prior  $\pi(\theta)$ 1. 0,15 spend some time being philosophical 20 2. Sample posterior  $\mathcal{P}(\theta|D)$ 15 200 0.FD use out-of-the-box MCMC tools such as  $\Omega_M$ emcee or MultiNest Mode SES-SN5VR+BAO+3v2m DES-SN5YB vs CMB make some triangle plots Model DES-SN5YR vs BAO+3x2p Flat-ACDM mpared to anarad to ElatACDA 3. Optionally compute evidence  $\mathcal{Z}(D)$ Flat-ACDM ACDM ACDM Flat\_wCDM e.g. nested sampling or parallel tempering Flat-wCDM Flat-w-w\_CDM ► do some model comparison (i.e. science) Flat-wow-CDM -2.5 2.5 talk about tensions  $\Delta(\ln BE)$  compared -2.5 to FlatACDM  $A \ln S$ 

#### <wh260@cam.ac.uk>

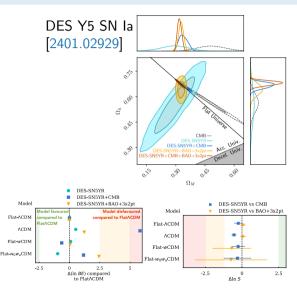
The standard approach if you are fortunate DES Y5 SN la enough to have a likelihood function  $\mathcal{L}(D|\theta)$ : 2401.02929 Likelihood × Prior  $\mathcal{P}(\theta|D) = \frac{\mathcal{L}(D|\theta)\pi(\theta)}{\mathcal{Z}(D)}$ Posterior =0.70 Evidence 0.60 ΩV Define prior  $\pi(\theta)$ 1. 0,15 spend some time being philosophical 20 2. Sample posterior  $\mathcal{P}(\theta|D)$ 12 30 0.GC use out-of-the-box MCMC tools such as  $\Omega_M$ emcee or MultiNest Mode SES-SN5VR+BAO+3v2m DES-SN5YB vs CMB make some triangle plots Model DES-SN5YR vs BAO+3x2p mpared to FlatACDM Flat-ACDM mpared to 3. Optionally compute evidence  $\mathcal{Z}(D)$ Flat-ACDM ACDM ACDM Flat\_wCDM e.g. nested sampling or parallel tempering Flat-wCDM Flat-w-w\_CDM ► do some model comparison (i.e. science) Flat-wow-CDM -2.5 2.5 talk about tensions  $\Delta(\ln BE)$  compared -2.5 to FlatACDM  $A \ln S$ 

#### <wh260@cam.ac.uk>

The standard approach if you are fortunate enough to have a likelihood function  $\mathcal{L}(D|\theta)$ :

 $P(\theta|D)P(D) = P(\theta, D) = P(D|\theta)P(\theta),$ 

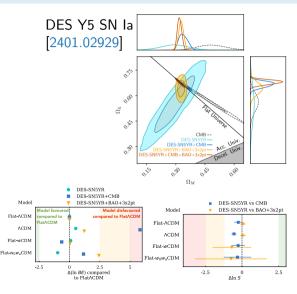
- 1. Define prior  $\pi(\theta)$ 
  - spend some time being philosophical
- 2. Sample posterior  $\mathcal{P}(\theta|D)$ 
  - use out-of-the-box MCMC tools such as emcee or MultiNest
  - make some triangle plots
- 3. Optionally compute evidence  $\mathcal{Z}(D)$ 
  - e.g. nested sampling or parallel tempering
  - do some model comparison (i.e. science)
  - talk about tensions



#### <wh260@cam.ac.uk>

The standard approach if you are fortunate enough to have a likelihood function  $\mathcal{L}(D|\theta)$ :

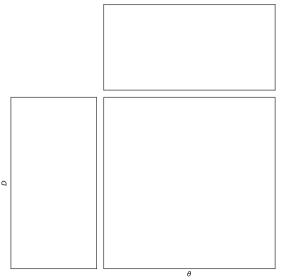
- $\mathcal{P} \times \mathcal{Z} = \mathcal{J} = \mathcal{L} \times \pi$ , Joint  $= \mathcal{J} = P(\theta, D)$
- **1**. Define prior  $\pi(\theta)$ 
  - spend some time being philosophical
- 2. Sample posterior  $\mathcal{P}(\theta|D)$ 
  - use out-of-the-box MCMC tools such as emcee or MultiNest
  - make some triangle plots
- 3. Optionally compute evidence  $\mathcal{Z}(D)$ 
  - e.g. nested sampling or parallel tempering
  - do some model comparison (i.e. science)
  - talk about tensions



#### <wh260@cam.ac.uk>

- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [:handley-lab/lsbi].

<wh260@cam.ac.uk>



- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].

<wh260@cam.ac.uk>

## $c(D|\theta) =$ A willhandley.co.uk/talks

15

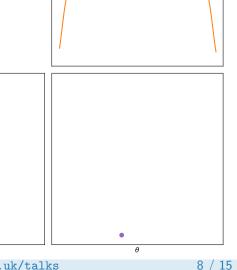
- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [:handley-lab/lsbi].

<wh260@cam.ac.uk>

# $c(D|\theta) =$ A willhandley.co.uk/talks 15

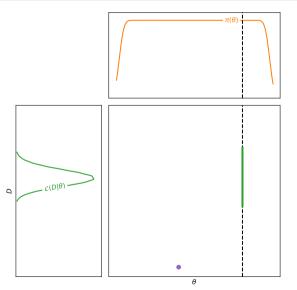
- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \to D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior  $\pi(\theta)$  can generate samples from joint distribution  $\mathcal{J}(\theta, D) = \mathcal{L}(D|\theta)\pi(\theta)$ the "probability of everything".
- Task of SBI is take joint  $\mathcal{J}$  samples and learn posterior  $\mathcal{P}(\theta|D)$  and evidence  $\mathcal{Z}(D)$ and possibly likelihood  $\mathcal{L}(D|\theta)$ .
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [:handley-lab/lsbi].

<wh260@cam.ac.uk>



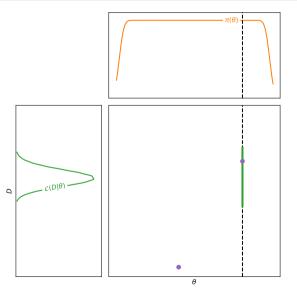
- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- ► Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].





- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- ► Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].





- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].

<wh260@cam.ac.uk>

# $c(D|\theta) =$ A willhandley.co.uk/talks

15

- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].

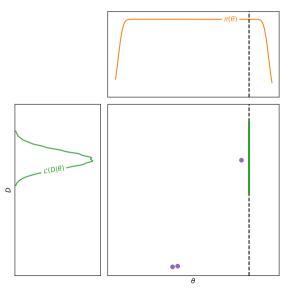
<wh260@cam.ac.uk>

## 



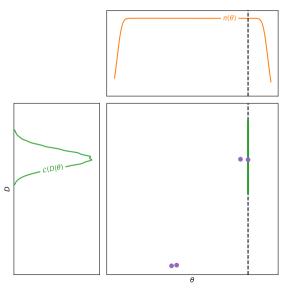
- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- ► Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [:handley-lab/lsbi].





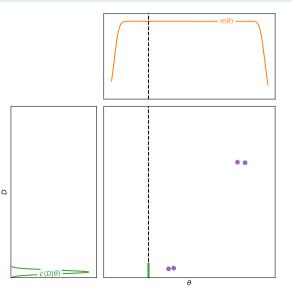
- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- ► Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [Q:handley-lab/lsbi].





- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- ► Task of SBI is take joint  $\mathcal{J}$  samples and learn posterior  $\mathcal{P}(\theta|D)$  and evidence  $\mathcal{Z}(D)$ and possibly likelihood  $\mathcal{L}(D|\theta)$ .
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].

<wh260@cam.ac.uk>



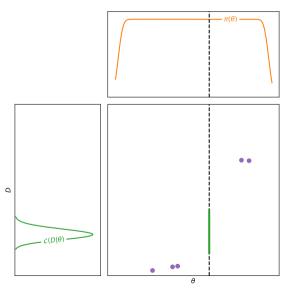
- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- ► Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].

<wh260@cam.ac.uk>

# . . ... A

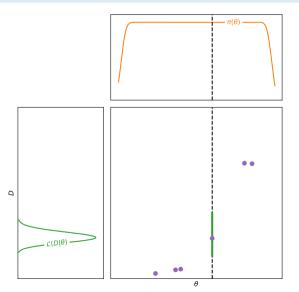
- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(θ|D) and evidence *Z*(D) and possibly likelihood *L*(D|θ).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].





- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [:handley-lab/lsbi].

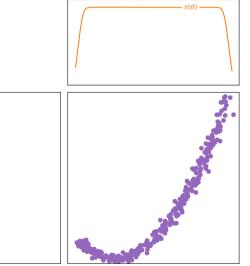




- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].



## willhandley.co.uk/talks



#### 8 / 15

- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].

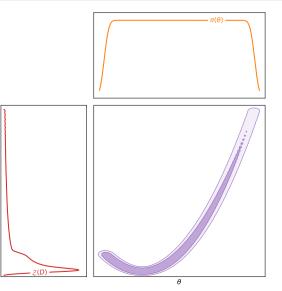


#### willhandley.co.uk/talks



A

- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].

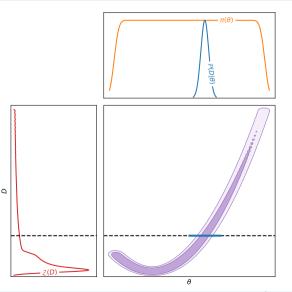


<wh260@cam.ac.uk>

#### willhandley.co.uk/talks

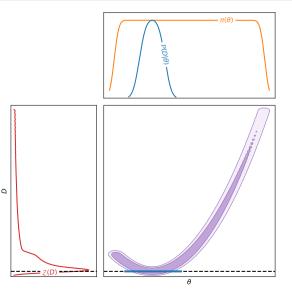
Ω

- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(θ|D) and evidence *Z*(D) and possibly likelihood *L*(D|θ).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].



<wh260@cam.ac.uk>

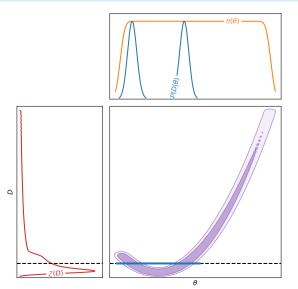
- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].



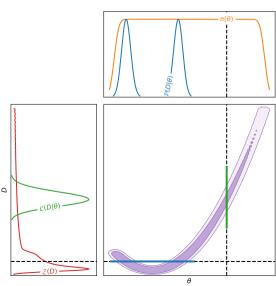
<wh260@cam.ac.uk>

- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- ► Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [S:handley-lab/lsbi].





- What do you do if you don't know  $\mathcal{L}(D|\theta)$ ?
- If you have a simulator/forward model  $\theta \rightarrow D$  defines an *implicit* likelihood  $\mathcal{L}$ .
- Simulator generates samples from  $\mathcal{L}(\cdot|\theta)$ .
- With a prior π(θ) can generate samples from joint distribution J(θ, D) = L(D|θ)π(θ) the "probability of everything".
- ► Task of SBI is take joint *J* samples and learn posterior *P*(*θ*|*D*) and evidence *Z*(*D*) and possibly likelihood *L*(*D*|*θ*).
- Present state of the art achieves this using machine learning (neural networks).
  - My group's research tries to removes machine learning [:handley-lab/lsbi].



<wh260@cam.ac.uk>

## Why SBI?

SBI is useful because:

- 1. If you don't have a likelihood, you can still do inference
  - This is the usual case beyond CMB cosmology
- 2. Faster than LBI
  - emulation also applies to LBI in principle
- 3. No need to pragmatically encode fiducial cosmologies
  - Covariance computation implicitly encoded in simulations
  - Highly relevant for disentangling tensions & systematics
- 4. Equips AI/ML with Bayesian interpretability
- 5. Lower barrier to entry than LBI
  - Much easier to forward model a systematic
  - Emerging set of plug-and-play packages
  - For this reason alone, it will come to dominate scientific inference



<wh260@cam.ac.uk>

## **SBI** in astrophysics

- 2024 has been the year it has started to be applied to real data.
- Mostly for weak lensing
- However: SBI requires mock data generation code
- Most data analysis codes were built before the generative paradigm.
- It's still a lot of work to upgrade cosmological likelihoods to be able to do this (e.g. plik & camspec).
- [O:smsharma/awesome-neural-sbi]

#### Investigating the turbulent hot gas in X-COP galaxy clusters

S. Dupourqué<sup>1</sup>, N. Clerc<sup>1</sup>, E. Pointecouteau<sup>1</sup>, D. Eckert<sup>2</sup>, S. Ettori<sup>3</sup>, and F. Vazza<sup>4,5,6</sup>

Dark Energy Survey Year 3 results: simulation-based cosmological inference with wavelet harmonics, scattering transforms, and moments of weak lensing mass maps II. Cosmological results

M. Gatti,<sup>1, +</sup> G. Campailla,<sup>2</sup> N. Jeffrey,<sup>3</sup> L. Whiteway,<sup>3</sup> A. Porredon,<sup>4</sup> J. Prat,<sup>5</sup> J. Williamson,<sup>3</sup> M. Raveri,<sup>2</sup> B.

#### Neural Posterior Estimation with guaranteed exact coverage: the ringdown of GW150914

Marco Crisostomi<sup>1,2</sup>, Kallol Dey<sup>3</sup>, Enrico Barausse<sup>1,2</sup>, Roberto Trotta<sup>1,2,4,5</sup>

Applying Simulation-Based Inference to Spectral and Spatial Information from the Galactic Center Gamma-Ray Excess

Katharena Christy,<sup>a</sup> Eric J. Baxter,<sup>b</sup> Jason Kumar<sup>a</sup>

#### KiDS-1000 and DES-Y1 combined: Cosmology from peak count statistics

Joachim Hamois-Déraps<sup>14</sup>, Sven Heydenreich<sup>2</sup>, Benjamin Giblin<sup>3</sup>, Nicolas Martinet<sup>4</sup>, Tilman Tröster<sup>6</sup>, Marika Asgari<sup>1,63</sup>, Pierre Burger<sup>6,8,10</sup> Tiago Castro<sup>1,12,13,14</sup>, Klaus Dolag<sup>15</sup>, Catherine Heymans<sup>3,16</sup>, Hendrik Hildebrandt<sup>16</sup>, Benjamin Joachimi<sup>17</sup> & Angus H. Wright<sup>16</sup>

#### KIDS-SBI: Simulation-Based Inference Analysis of KIDS-1000 Cosmic Shear

Maximilian von Wietersheim-Kramsta<sup>1,2,3</sup>, Kiyam Lin<sup>1</sup>, Nicolas Tessore<sup>1</sup>, Benjamin Joachimi<sup>1</sup>, Arthur Loureiro<sup>6,5</sup>, Robert Reischke<sup>6,7</sup>, and Angus H. Wright<sup>7</sup>

## Simulation-based inference of deep fields: galaxy population model and redshift distributions

Beatrice Moser,<sup>a,1</sup> Tomasz Kacprzak,<sup>a,b</sup> Silvan Fischbacher,<sup>a</sup> Alexandre Refregier,<sup>a</sup> Dominic Grimm,<sup>a</sup> Luca Tortorelli<sup>c</sup>

SDBIG: Cosmological Constraints using Simulation-Based Inference of Galaxy Clustering with Marked Power Spectra

ELEMA MASSARA  $\bigcirc$ <sup>1,2,\*</sup> Changedon Hars  $\bigcirc$ <sup>3</sup> Michael Eckenberg, <sup>6</sup> Serley Ho,<sup>5</sup> James Hou,<sup>6,7</sup> Pareo Lemos,<sup>6,6,8,5</sup> Chirley Mora,<sup>6,8</sup> Araksik Moransererasi Dergan  $\bigcirc$ <sup>9,111</sup> Liam Pareer,<sup>6,12</sup> and Bienno Rolandon-Sante Handerand  $\bigcirc$ <sup>4</sup>

#### Cosmology from HSC Y1 Weak Lensing with Combined Higher-Order Statistics and Simulation-based Inference

Camila P. Novaes<sup>1,2,3</sup>,\* Leander Thiele<sup>2,3</sup>,† Joaquin Armijo<sup>2,3</sup>, Sihao Cheng<sup>4,5</sup>, Jessica A. Cowell<sup>2,3,6</sup>, Gabriela A. Marques<sup>7,8</sup>, Elisa G. M. Ferreira<sup>2,3</sup>, Masato Shirasaki<sup>9,10</sup>, Ken Osato<sup>11,12,2</sup>, and Jia Liu<sup>2,3</sup>

15

## **Neural Ratio Estimation**

- SBI flavours: github.com/sbi-dev/sbi
  - NPE Neural posterior estimation
  - NLE Neural likelihood estimation
  - NJE Neural joint estimation
  - NRE Neural ratio estimation
- NRE recap:
  - 1. Generate joint samples  $(\theta, D) \sim \mathcal{J}$ 
    - straightforward if you have a simulator:  $\theta \sim \pi(\cdot)$ ,  $D \sim \mathcal{L}(\cdot|\theta)$
  - 2. Generate separated samples  $\theta \sim \pi$ ,  $D \sim \mathcal{Z}$ 
    - aside: can shortcut step 2 by scrambling the (θ, D) pairings from step 1
  - 3. Train probabilistic classifier p to distinguish whether  $(\theta, D)$  came from  $\mathcal{J}$  or  $\pi \times \mathcal{Z}$ .

4. 
$$\frac{p}{1-p} = r = \frac{P(\theta,D)}{P(\theta)P(D)} = \frac{\mathcal{J}}{\pi \times \mathcal{Z}} = \frac{\mathcal{L}}{\mathcal{Z}} = \frac{\mathcal{P}}{\pi}.$$

5. Use ratio *r* for parameter estimation  $\mathcal{P} = r \times \pi$ 

#### willhandley.co.uk/talks

θ

D

p

## **Neural Ratio Estimation**

- SBI flavours: github.com/sbi-dev/sbi
  - NPE Neural posterior estimation
  - NLE Neural likelihood estimation
  - NJE Neural joint estimation
  - NRE Neural ratio estimation
- NRE recap:
  - 1. Generate joint samples  $(\theta, D) \sim \mathcal{J}$ 
    - straightforward if you have a simulator:  $\theta \sim \pi(\cdot)$ ,  $D \sim \mathcal{L}(\cdot|\theta)$
  - 2. Generate separated samples  $\theta \sim \pi$ ,  $D \sim \mathcal{Z}$ 
    - aside: can shortcut step 2 by scrambling the (θ, D) pairings from step 1
  - 3. Train probabilistic classifier p to distinguish whether  $(\theta, D)$  came from  $\mathcal{J}$  or  $\pi \times \mathcal{Z}$ .

4. 
$$\frac{p}{1-p} = r = \frac{P(\theta,D)}{P(\theta)P(D)} = \frac{\mathcal{J}}{\pi \times \mathcal{Z}} = \frac{\mathcal{L}}{\mathcal{Z}} = \frac{\mathcal{P}}{\pi}$$

5. Use ratio *r* for parameter estimation  $\mathcal{P} = r \times \pi$ 

## **Bayesian proof**

- Let  $M_{\mathcal{J}}$ :  $(\theta, D) \sim \mathcal{J}$ ,  $M_{\pi \mathcal{Z}}$ :  $(\theta, D) \sim \pi \times \mathcal{Z}$
- Classifier gives  $p(\theta, D) = P(M_{\mathcal{J}}|\theta, D) = 1 - P(M_{\pi Z}|\theta, D)$
- ▶ Bayes theorem then shows  $\frac{p}{1-p} = \frac{P(M_{\mathcal{J}}|\theta,D)}{P(M_{\pi Z}|\theta,D)} = \frac{P(\theta,D|M_{\mathcal{J}})P(M_{\mathcal{J}})}{P(\theta,D|M_{\pi Z})P(M_{\pi Z})} = \frac{\mathcal{J}}{\pi Z},$ where we have assumed
  - $P(M_{\mathcal{J}}) = P(M_{\pi \mathcal{Z}}),$

and by definition

- $\mathcal{J}(\theta, D) = P(\theta, D|M_{\mathcal{J}})$
- $\pi(\theta)\mathcal{Z}(D) = P(\theta, D|M_{\pi \mathcal{Z}}).$

#### <wh260@cam.ac.uk>

## **Neural Ratio Estimation**

- SBI flavours: github.com/sbi-dev/sbi
  - NPE Neural posterior estimation
  - NLE Neural likelihood estimation
  - NJE Neural joint estimation
  - NRE Neural ratio estimation
- NRE recap:
  - 1. Generate joint samples  $(\theta, D) \sim \mathcal{J}$ 
    - straightforward if you have a simulator:  $\theta \sim \pi(\cdot)$ ,  $D \sim \mathcal{L}(\cdot|\theta)$
  - 2. Generate separated samples  $\theta \sim \pi$ ,  $D \sim \mathcal{Z}$ 
    - aside: can shortcut step 2 by scrambling the (θ, D) pairings from step 1
  - 3. Train probabilistic classifier p to distinguish whether  $(\theta, D)$  came from  $\mathcal{J}$  or  $\pi \times \mathcal{Z}$ .

4. 
$$\frac{p}{1-p} = r = \frac{P(\theta,D)}{P(\theta)P(D)} = \frac{\mathcal{J}}{\pi \times \mathcal{Z}} = \frac{\mathcal{L}}{\mathcal{Z}} = \frac{\mathcal{P}}{\pi}$$

5. Use ratio *r* for parameter estimation  $\mathcal{P} = \mathbf{r} \times \pi$ 

## Why I like NRE

- The link between classification and inference is profound.
- Density estimation is hard Dimensionless r divides out the hard-to-calculate parts.

## Why I don't like NRE

- Practical implementations require marginalisation [2107.01214], or autoregression [2308.08597].
- Model comparison and parameter estimation are separate [2305.11241].

#### <wh260@cam.ac.uk>

## I want (my student) to get started with SBI...

## the swyft package

- Ratio estimation
- astro/cosmology specific examples

swyft.readthedocs.io/en/stable

## the pydelfi package

- Neural density estimation
- astro/cosmology specific examples

justinalsing.github.io/pydelfi

## the sbi package

- General package
- Not domain specific
- A lot of (opaquely named) methods

sbi-dev.github.io/sbi/latest/tutorials

All methods generally require:

- A forward simulator
- A data compressor

All methods either:

- "Amortized" over data D
- "Sequential" tuning to D<sub>obs</sub>

willhandley.co.uk/talks

<wh260@cam.ac.uk>

## **GPU-accelerated inference**

CMB cosmopower [2106.03846]

- CMB candl [2401.13433]
- SNe BayesSN [2401.08755]
- SGW Eryn [2303.02164]
  - GW redback [2308.12806]
  - GW ripple [2302.05329]
  - EP ExoJAX [2105.14782]
  - X jaxspec [2409.05757]

[C:JAXtronomy]

- Increase in the number of cosmological codes written for GPUs (particularly jax).
- Over the next few years, more and more analyses will be done on GPUs.
- Several trends trigger this
  - the rise of machine learning, whose linear algebra is well-suited to GPUs
  - the creation of usable languages for GPU programming (e.g. jax, pytorch, tensorflow)
  - the rise of large language models, which ease writing codes for GPUs
- Prediction: low-power GPUs (likely ARM-based) will become the norm for scientific computing.



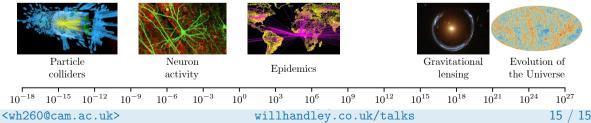
- very recent work over the past month
- Have implemented a nested slice sampler in blackjax [O:blackjax-devs/blackjax/pull/755].

```
pip install git+https://github.com/handley-lab/blackjax@nested_sampling
import blackjax.ns.adaptive
```

- Think MultiNest for jax.
- Plugs into jim [S:kazewong/jim] and ripple [2302.05329]



- Inference bridges theory and experiment, crucial for extracting information from data.
- Simulation-Based Inference (SBI) enables inference when the likelihood is intractable, using simulations and machine learning. SBI is becoming increasingly popular for complex astrophysical analyses.
- GPU-accelerated inference is transforming the field, allowing faster and more complex computations. Tools like jax are empowering a new generation of GPU-ready inference codes.



## Frontiers of simulation based inference [1911.01429]