

CMS Upgrade

and its impact on Flavour Physics

Motivations

- LHC will undergo sizeable upgrades in the near and in longer terms
 - Luminosity increase
 - Pile-up and Background increase

Increased trigger rate and data-event size
- Purpose of CMS upgrades :
 - maintain / improve wrt present performances, despite the more difficult operating conditions
 - ensure radiation resistance, and easy replacements during short shutdown
- Major and minor interventions
 - mostly aimed at High- p_T Physics
 - beneficent for B-Physics as well

FOCUS for this talk

Upgrade Plan



Upgrade Plan

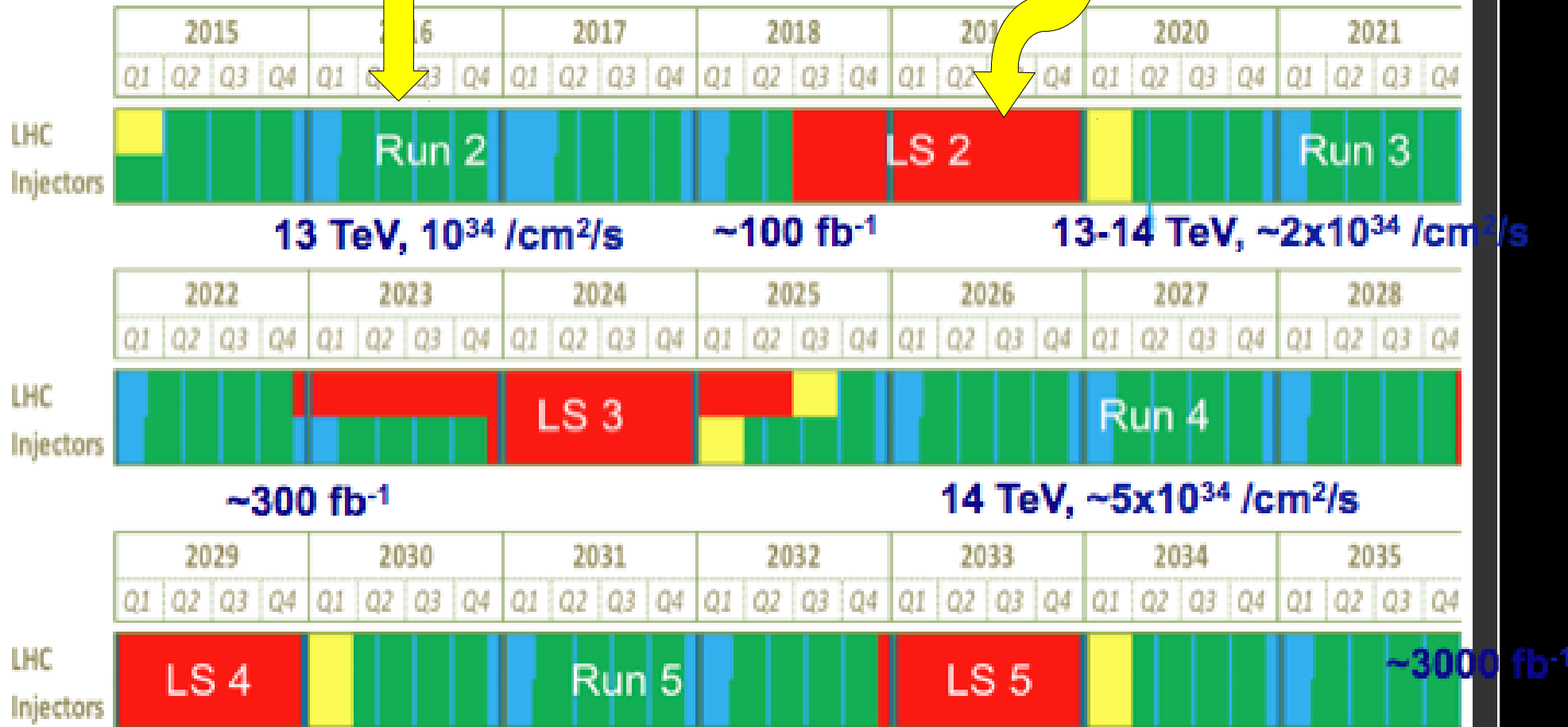
2015 : RUN with smaller beam pipe,
useful for next upgrade



Upgrade Plan

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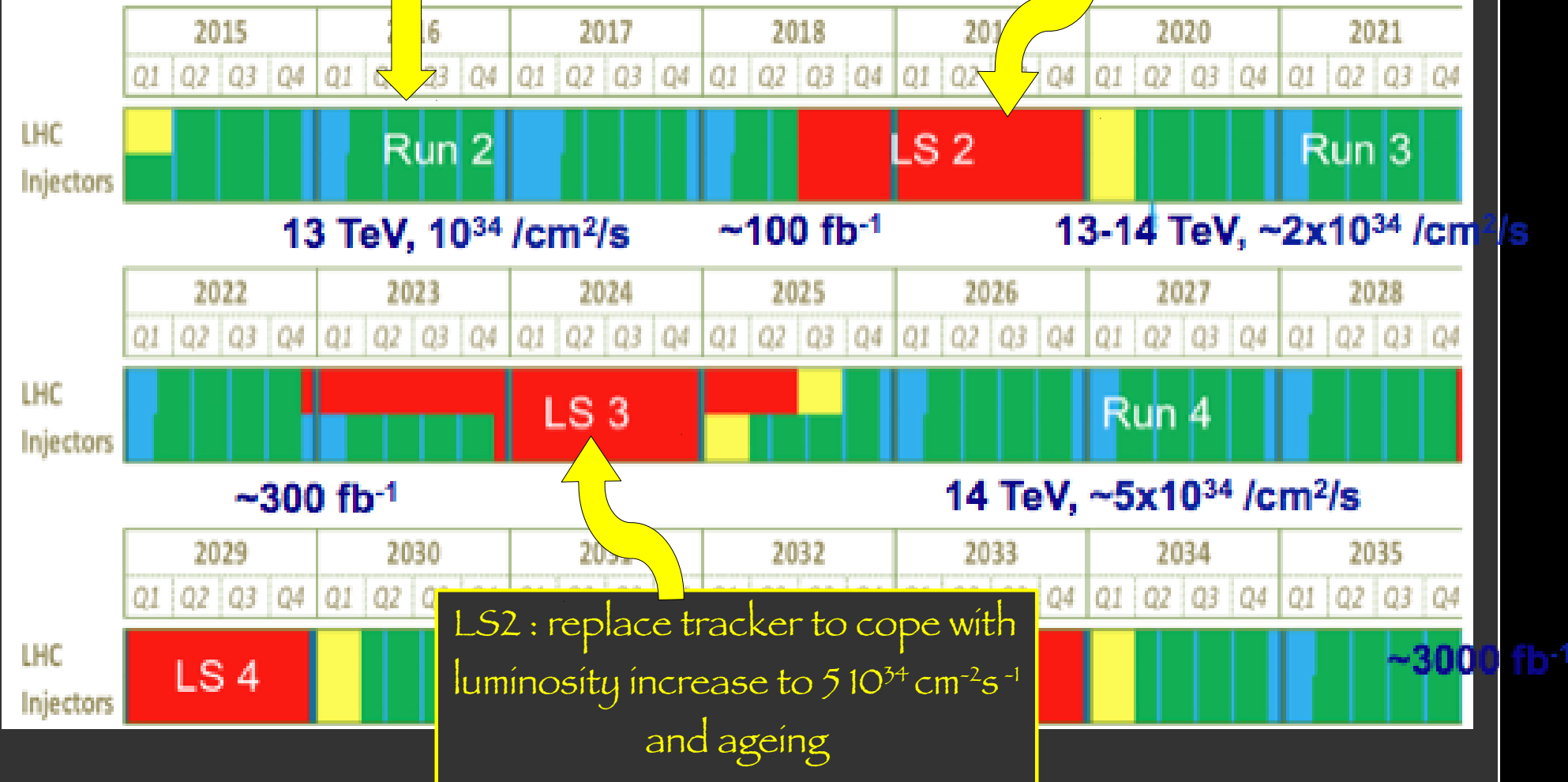
LS2 : replace pixels to cope with luminosity increase to $2 \cdot 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$



Upgrade Plan

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PIXEL Upgrade

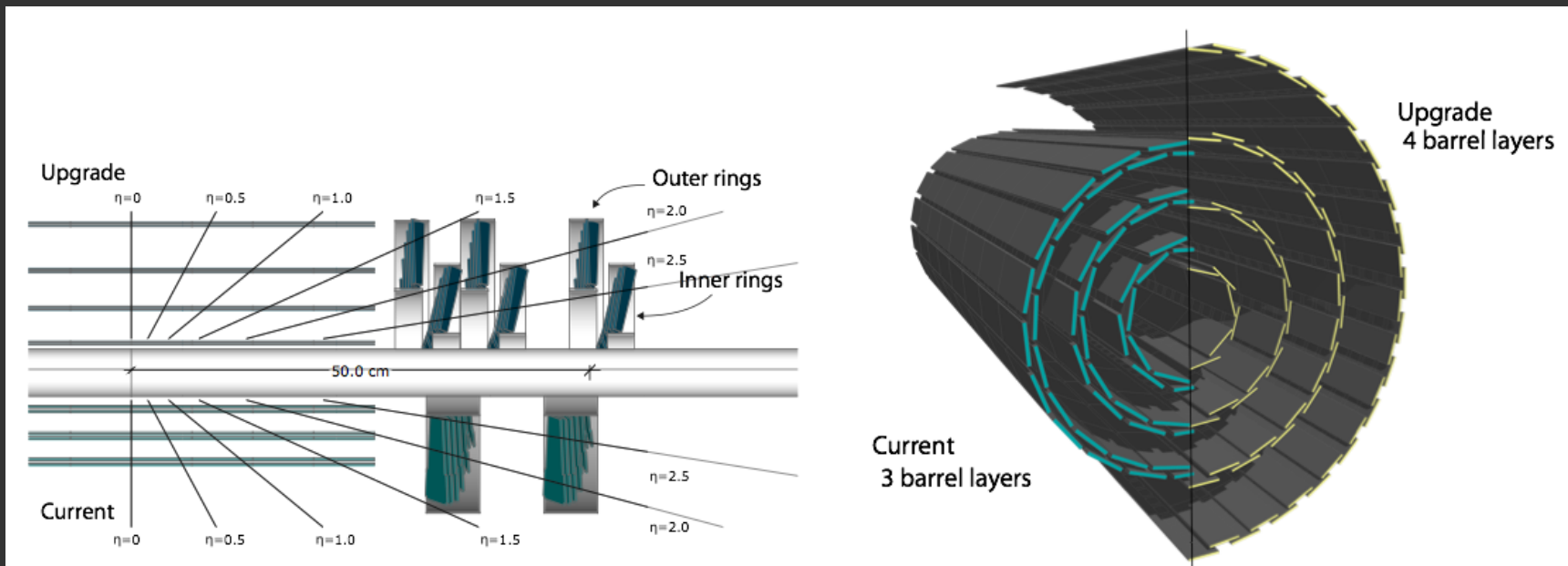
- Main features

- four layers, inner closer to interaction region
- new readout, reduce data loss
- new cooling, lighter mechanical support, electronic & connections out of Tk volume
- overall easier access

Exploit smaller beam pipe
Increase precision and redundancy

Reduce material

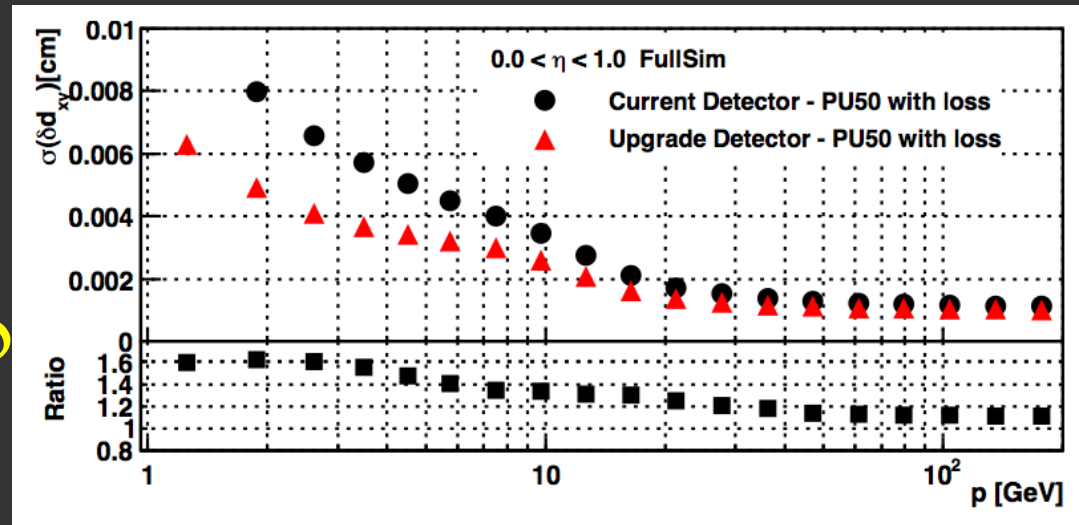
Operation, replacement



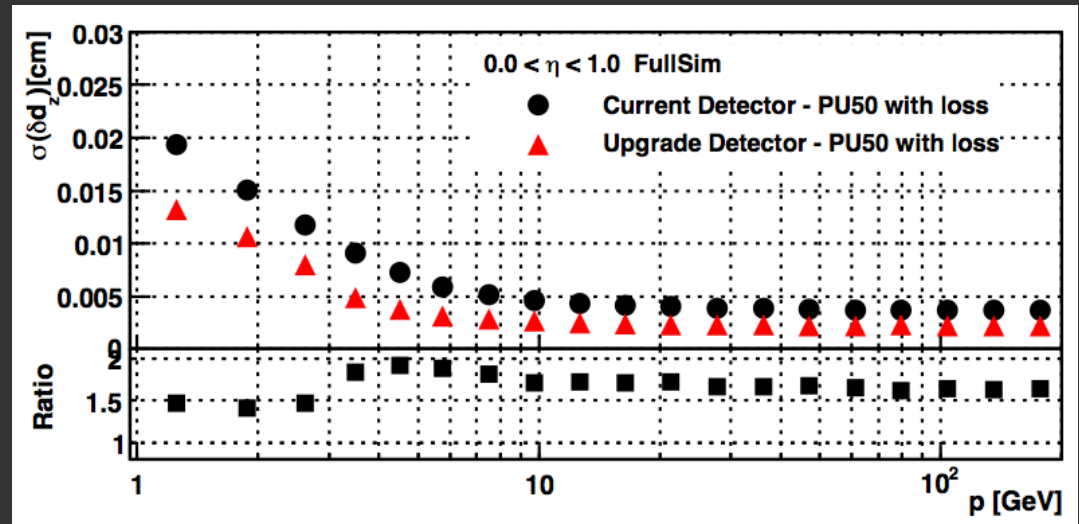
Upgraded Pixel Performance

- Main benefit at low p_T
- Helpful for B-Physics

CERN-LHCC-2012-016



Impact Parameter Resolution, xy



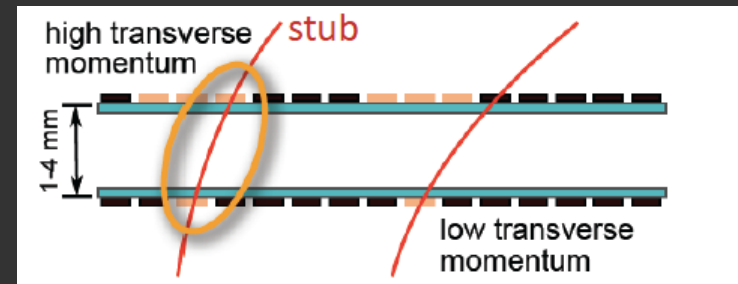
Impact Parameter Resolution, z

Upgraded Tracking

- Radiation hardness
- Granularity
 - resolve 150-200 collisions per bunch, with few % occupancy
- Reduce material (nuclear interaction, γ conversion)
- Repair modules at short stops
- Provide L1 trigger

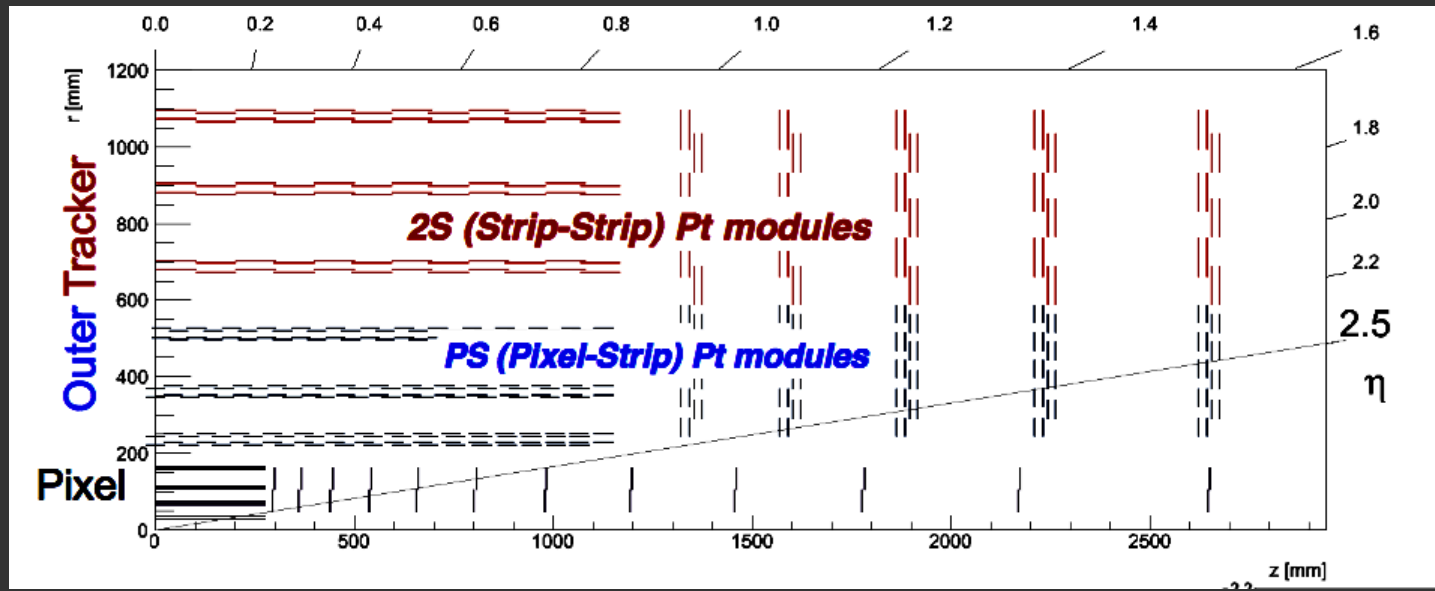
Upgraded Tracking

- Radiation hardness
- Granularity
 - resolve 150-200 collisions per bunch, with few % occupancy
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- Provide L1 trigger
- Measure (high) p_T on board the modules:
 - two close modules red-out by one single chip

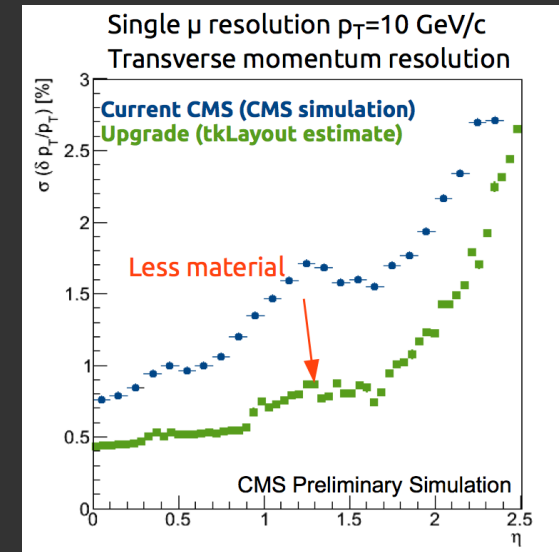
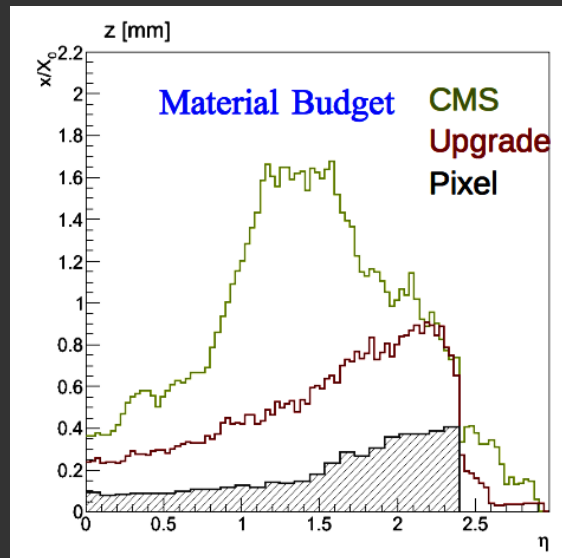


Inner : Pixel+Strip (PS)
Outer : Strip+Strip (2S)

Upgraded Tracker Layout & Performance



- Sizeable reduction of material
- Sizeable Improvement in p_T resolution

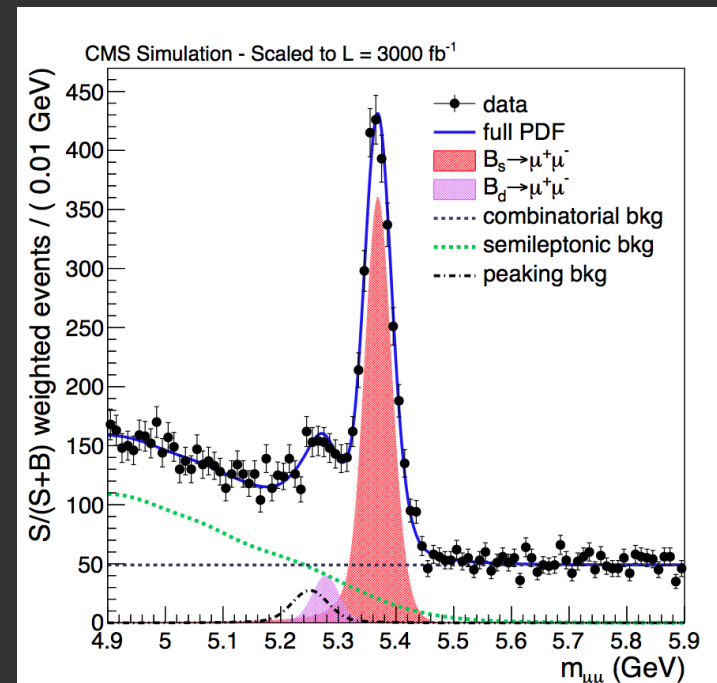
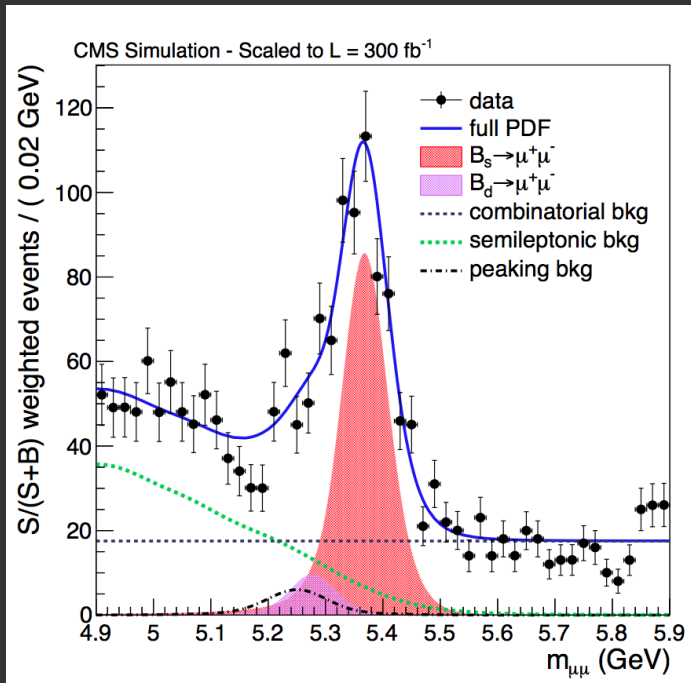


Benchmark : $B \rightarrow \mu\mu$

Hypothesis :

- L1 track-Trigger allows same L1 thresholds as now ($p_T(\mu) > 3 \text{ GeV}$)
- Efficiency :
 - pileup : $\epsilon(\mu\mu) \downarrow 30\%$ (isolation)
 - μ reco & trigger : $\epsilon(\mu\mu) \downarrow 2 \times 5\%$
- $\sigma(\text{syst})$:
 - f_s/f_u : 5% (now) \rightarrow 3%
 - Normalization ($B^+ \rightarrow \psi K^+$) : $3\%^{(\text{BR})} \oplus 5\% / \sqrt{\mathcal{L}_{\text{INT}}/20 \text{ fb}^{-1}}$ (Rate)
 - Peaking Background : $10\%^{(\text{BR})} \oplus 50\% / \sqrt{\mathcal{L}_{\text{INT}}/20 \text{ fb}^{-1}}$ (Control Sample)
 - Semileptonic Background : $20\%^{(\text{BR})} \oplus 50\% / \sqrt{\mathcal{L}_{\text{INT}}/20 \text{ fb}^{-1}}$ (Control Sample)
- Resolution:
 - $\downarrow 1.6$ (Barrell) $\downarrow 1.2$ (Forward)
 - ignore improvement due to 1st pixel layer

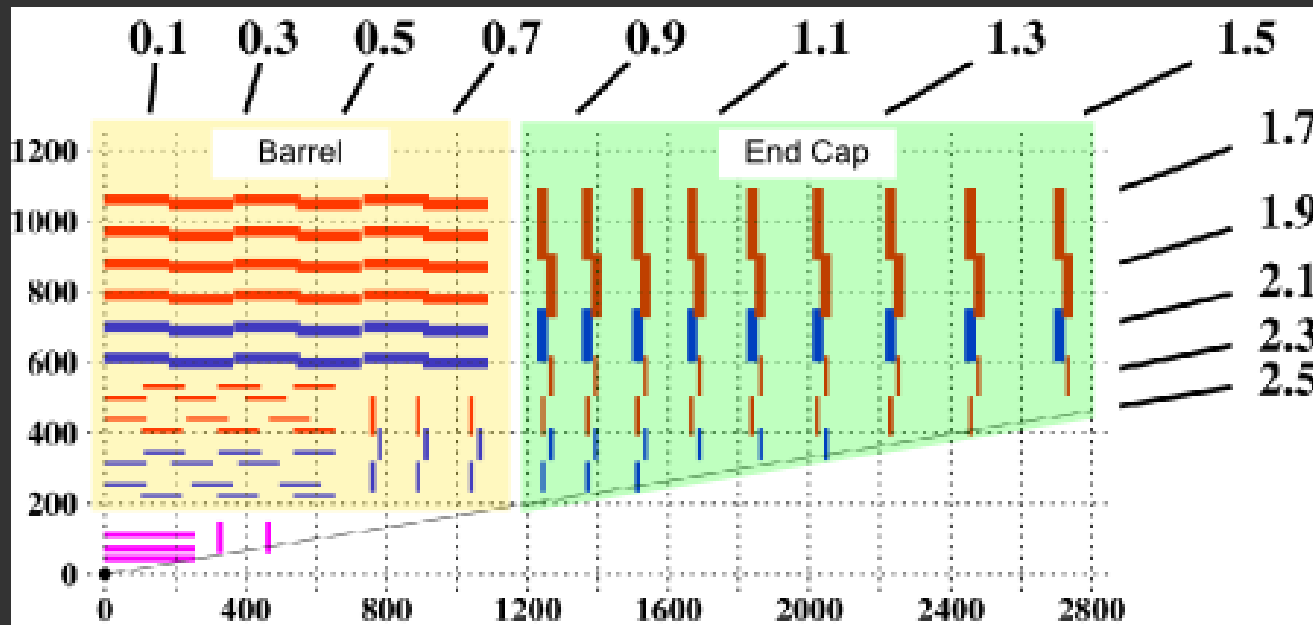
$B \rightarrow \mu\mu$: expectations



$L \text{ (fb}^{-1}\text{)}$	No. of B_s^0	No. of B^0	$\delta B/B(B_s^0 \rightarrow \mu^+\mu^-)$	$\delta B/B(B^0 \rightarrow \mu^+\mu^-)$	B^0 sign.	$\delta \frac{B(B^0 \rightarrow \mu^+\mu^-)}{B(B_s^0 \rightarrow \mu^+\mu^-)}$
20	16.5	2.0	35%	>100%	$0.0\text{--}1.5 \sigma$	>100%
100	144	18	15%	66%	$0.5\text{--}2.4 \sigma$	71%
300	433	54	12%	45%	$1.3\text{--}3.3 \sigma$	47%
3000	2096	256	12%	18%	$5.4\text{--}7.6 \sigma$	21%

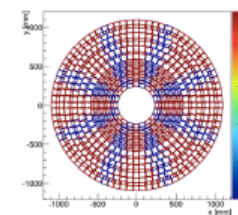
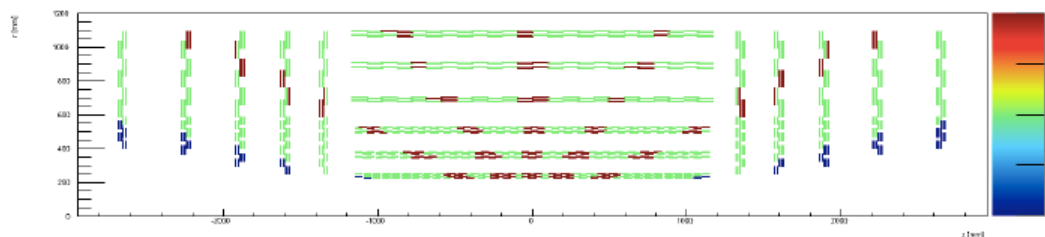
- 3000 fb^{-1} : statistic is not an issue
- Use just barrel events, resolution is enough to separate $B_d/B_s/B \rightarrow hh'$
- $Br(B_d) > 5 \sigma$

Backup: current tracker layout



Backup : Hardware Track Trigger

- Subdivide tracker into trigger towers
- $8(r-\varphi) \times 6(r-z)$ trigger sectors (some 10% overlapping)
 - Each sector ~ 200 stubs on average; tails up to ~ 500 stubs/event in 140 evts pileup+ttbar
 - About 600 Gb/s per one trigger tower



- Send data to Track-finding processors
- Full mesh ATCA shelves
 - “40G” full-mesh backplane on 14 slots = 7.2 Tb/s
 - time multiplexing data transfer from a set of receiving boards to pattern recognition and track finding engine
 - $O(10)$ time multiplexed at the shelf level

